

EXAMPLE: CYCLOSTATIONARY PROCESS

ECE - 541, FALL 2004

$$X(t) = A \cos(\omega_c t) + B \sin(\omega_c t)$$

$$\left. \begin{array}{l} A \sim N(\mu_1, \sigma_1^2) \\ B \sim N(\mu_2, \sigma_2^2) \end{array} \right\} A \text{ \& } B \text{ are uncorrelated}$$

First-order Statistics:

$$t_0 \in \mathbb{T}(\mathbb{R}^1)$$

$$X(t_0) = A \cos(\omega_c t_0) + B \sin(\omega_c t_0)$$

$$\mu_x(t_0) = E\{A\} \cos(\omega_c t_0) + E\{B\} \sin(\omega_c t_0)$$

$$\mu_x(t_0) = \mu_1 \cos(\omega_c t_0) + \mu_2 \sin(\omega_c t_0)$$

$$\mu_x(t), t \in \mathbb{R}^1 = \mu_1 \cos(\omega_c t) + \mu_2 \sin(\omega_c t)$$

$$\mu_x(t) = \sqrt{\mu_1^2 + \mu_2^2} \cos(\omega_c t - \tan^{-1}(\frac{\mu_2}{\mu_1}))$$

$$\mu_x(t) = \mu_x(t + 2\pi/\omega_c)$$

$$\begin{aligned} E\{X^2(t)\} &= \mu_1^2 \cos^2(\omega_c t) + \mu_2^2 \sin^2(\omega_c t) + \sigma_1^2 \cos^2(\omega_c t) \\ &\quad + 2\mu_1 \mu_2 \cos(\omega_c t) \sin(\omega_c t) + \sigma_2^2 \sin^2(\omega_c t) \end{aligned}$$

$$\begin{aligned} \sigma_x^2(t) &= E\{X^2(t)\} - \mu_x^2(t) \\ &= \sigma_1^2 \cos^2(\omega_c t) + \sigma_2^2 \sin^2(\omega_c t) \end{aligned}$$

$$\sigma_x^2(t) = \frac{\sigma_1^2 + \sigma_2^2}{2} + \frac{\sigma_1^2}{2} \cos(2\omega_c t) - \frac{\sigma_2^2}{2} \sin(2\omega_c t)$$

$$\sigma_x^2(t) = \sigma_x^2\left(t + \frac{2\pi}{2\omega_c}\right) \quad \left(\begin{array}{l} \text{First-order} \\ \text{Cyclostationary} \end{array} \right)$$

Second -- order Statistics

$$R_{xx}(t, \tau) = E\{X(t)X(t-\tau)\}$$

$$= E\left\{ [A \cos(\omega_c t) + B \sin(\omega_c t)] [\cos(\omega_c t - \omega_c \tau) A + B \sin(\omega_c t - \omega_c \tau)] \right\}$$

$$R_{xx}(t, \tau) = \frac{(\sigma_1^2 + \mu_1^2)}{2} \left\{ \cos(\omega_c \tau) + \cos(2\omega_c t - \omega_c \tau) \right\} + \frac{(\sigma_2^2 + \mu_2^2)}{2} \left\{ \cos(\omega_c \tau) - \cos(2\omega_c t - \omega_c \tau) \right\} + \mu_1 \mu_2 \left\{ \sin(2\omega_c t - \omega_c \tau) \right\}$$

$$R_{xx}(t, \tau) = R_{xx}\left(t + \frac{2\pi}{2\omega_c}, \tau\right) \quad (2^{\text{nd}} \text{ order cyclostationary})$$

$$\tilde{R}_{xx}(\tau) = \frac{\sigma_1^2 + \mu_1^2}{2} \cos(\omega_c \tau) + \frac{\sigma_2^2 + \mu_2^2}{2} \sin(\omega_c \tau)$$

Time - averaged ACF :

$$T_0^{(1)} = \frac{2\pi}{2\omega_c}, \quad T_0^{(2)} = \frac{2\pi}{2\omega_c}$$

Covariance :

$$\begin{aligned}
 C_{xx}(t, \tau) &= R_{xx}(t, \tau) - \mu_x(t) \mu_x(t-\tau) \\
 &= \left(\frac{\sigma_1^2 + \mu_1^2}{2} \right) \left\{ \cos(\omega_c \tau) + \cos(2\omega_c t - \omega_c \tau) \right\} \\
 &\quad + \left(\frac{\sigma_2^2 + \mu_2^2}{2} \right) \left\{ \cos(\omega_c \tau) - \cos(2\omega_c t - \omega_c \tau) \right\} \\
 &\quad + \mu_1 \mu_2 \sin(2\omega_c t - \omega_c \tau) \\
 &\quad - (\mu_1 \cos(\omega_c t) + \mu_2 \sin(\omega_c t)) \\
 &\quad \quad (\mu_1 \cos(\omega_c t - \omega_c \tau) + \mu_2 \sin(\omega_c t - \omega_c \tau)) \\
 &= \frac{\sigma_1^2}{2} [\cos(\omega_c \tau) + \cos(2\omega_c t - \omega_c \tau)] \\
 &\quad + \frac{\sigma_2^2}{2} [\cos(\omega_c \tau) - \cos(2\omega_c t - \omega_c \tau)]
 \end{aligned}$$

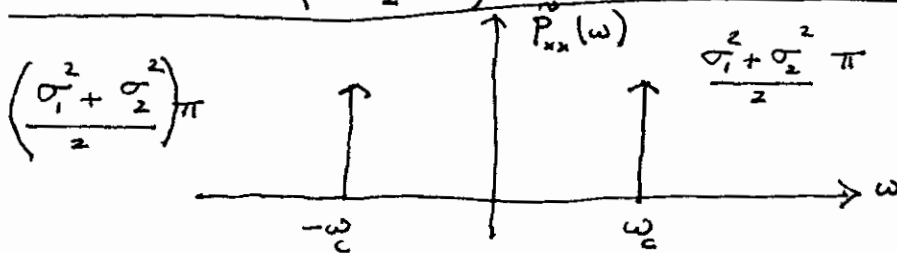
Time-averaged Covariance:

$$\tilde{C}_{xx}(\tau) = \frac{\sigma_1^2}{2} \cos(\omega_c \tau) + \frac{\sigma_2^2}{2} \cos(\omega_c \tau)$$

$$\tilde{C}_{xx}(\tau) = \frac{\sigma_1^2 + \sigma_2^2}{2} \cos(\omega_c \tau)$$

Time-averaged PSD:

$$\tilde{P}_{xx}(\omega) = \left(\frac{\sigma_1^2 + \sigma_2^2}{2} \right) \cdot \pi \left\{ \delta(\omega - \omega_c) + \delta(\omega + \omega_c) \right\}$$



$$\text{If } \mu_1 = \mu_2 = 0 \quad \& \quad \sigma_1^2 = \sigma_2^2 = \sigma^2$$

$$\Rightarrow \begin{array}{l} \mu_x(t) = 0 \\ \sigma_x^2(t) = \sigma^2 \end{array} \quad \Bigg| \quad R_{xx}(t, \tau) = \sigma^2 \cos(\omega_c \tau)$$

$\Rightarrow X(t)$ becomes WSS