

- Least-squares cost-function & solution non-iterative and not amenable to adaptation.
- Desire cost-function & solution to respond to change in signal environment.
- Want to avoid the least-squares prescription of matrix inversion.

- Cost-function:

$$J(\mathbf{w}[n], n) = \sum_{i=0}^n \lambda^{n-i} |e[i]|^2 = \sum_{i=0}^n \lambda^{n-i} (d[i] - \mathbf{w}^T[i] \mathbf{u}[i])^2$$

- Time-varying ACF and cross-correlation:

$$\{\tilde{\mathbf{R}}_{uu}\}_{pq} = \sum_{i=0}^n \lambda^{n-i} u[i-p] u[i-q], \quad \{\tilde{\mathbf{r}}_{du}\}_q = \sum_{i=0}^n \lambda^{n-i} d[i] u[i-q].$$

- Deterministic Normal Equations:

$$\tilde{\mathbf{R}}_{uu}[n] \mathbf{w}[n] = \tilde{\mathbf{r}}_{du}[n]$$

- Rank-one update:

$$\begin{aligned} \tilde{\mathbf{R}}_{uu}[n] &= \lambda \tilde{\mathbf{R}}_{uu}[n-1] + \mathbf{u}[n] \mathbf{u}^T[n] \\ \tilde{\mathbf{r}}_{du}[n] &= \lambda \tilde{\mathbf{r}}_{du}[n-1] + d[n] \mathbf{u}[n] \end{aligned}$$

- RLS gain vector:

$$\mathbf{g}[n] = \frac{\mathbf{P}[n-1] \mathbf{u}[n]}{\lambda + \mathbf{u}^T[n] \mathbf{P}[n-1] \mathbf{u}[n]}$$

- Inverse update using the matrix inversion lemma:

$$\mathbf{P}[n] = \frac{1}{\lambda} \mathbf{P}[n-1] - \frac{1}{\lambda} \mathbf{g}[n] \mathbf{u}^T[n] \mathbf{P}[n-1]$$

- RLS gain vector: solution to linear system:

$$\mathbf{g}[n] = \mathbf{P}[n] \mathbf{u}[n]$$

- Innovations process:

$$\alpha[n] = d[n] - \mathbf{w}^T[n-1] \mathbf{u}[n]$$

- Tap-weight update:

$$\mathbf{w}[n] = \mathbf{w}[n-1] + \alpha[n] \mathbf{g}[n]$$

- Whitening form of update:

$$\mathbf{w}[n] = \mathbf{w}[n-1] + \mathbf{P}[n] \mathbf{u}[n] \alpha[n].$$

- **Recursion for MMSE:**

$$J_{\min}[n] = \lambda J_{\min}[n-1] + \alpha[n]e[n]$$

- **Conversion factor:**

$$e[n] = (1 - \mathbf{g}^T[n]\mathbf{u}[n])\alpha[n]$$

- **Tap-weight update weights and smoothes innovations:**

$$\mathbf{w}[n] = \mathbf{w}[0] + \sum_{i=0}^n \mathbf{g}[i]\alpha[i]$$

- **Forget factor  $\lambda$  weights prior information relative to current information.**

- **Choice of  $\lambda$  determines speed of adaptation.**

- **Initialization of the RLS algorithm:**

$$\mathbf{w}[0] = 0, \quad \mathbf{P}[n] = \delta \mathbf{I}, \quad \delta > 0.$$

- **Whitening approach accounts for an order of magnitude improvement in convergence.**