

Lumped-Element Region

At any frequency, a transmission line can be shorted to a length below which the line operates in as a lumped-element circuit.

The boundary is defined by all combination of ω and l for which the magnitude of the *propagation coefficient* $l\gamma(\omega)$ remains **small**, i.e., **less than Δ** .

Δ is typically set to **0.25** (1/4)

$$|l\gamma(\omega)| < \Delta$$

l is the length of the transmission line

$\gamma(\omega)$ is the propagation coefficient (neper/m)

For typical digital transmission applications, the propagation coefficient **increases monotonically**.

Therefore, the inequality need be checked only at the maximum length and maximum anticipated frequency.

The boundary of the lumped element region can be approximated

$$\gamma = \sqrt{(j\omega L + R)(j\omega C + G)}$$

Start with propagation coefficient



Lumped-Element Region

Assume R , L and C are constants that do not vary with frequency.

Substituting into boundary condition, solve for l

$$|l\gamma(\omega)| < \Delta \quad \longrightarrow \quad l_{LE} = \left| \frac{0.25}{\sqrt{(j\omega L + R)(j\omega C)}} \right|$$

Since the boundary is 'fuzzy', we can substitute precise calculations with asymptotic approximations.

Here, the two boundaries are defined for l (meters) depending on the relative value of $j\omega L$ and R . Both are constrained by $\Delta = 0.25$.

$$l\gamma = l\sqrt{(j\omega L + R)(j\omega C)}$$

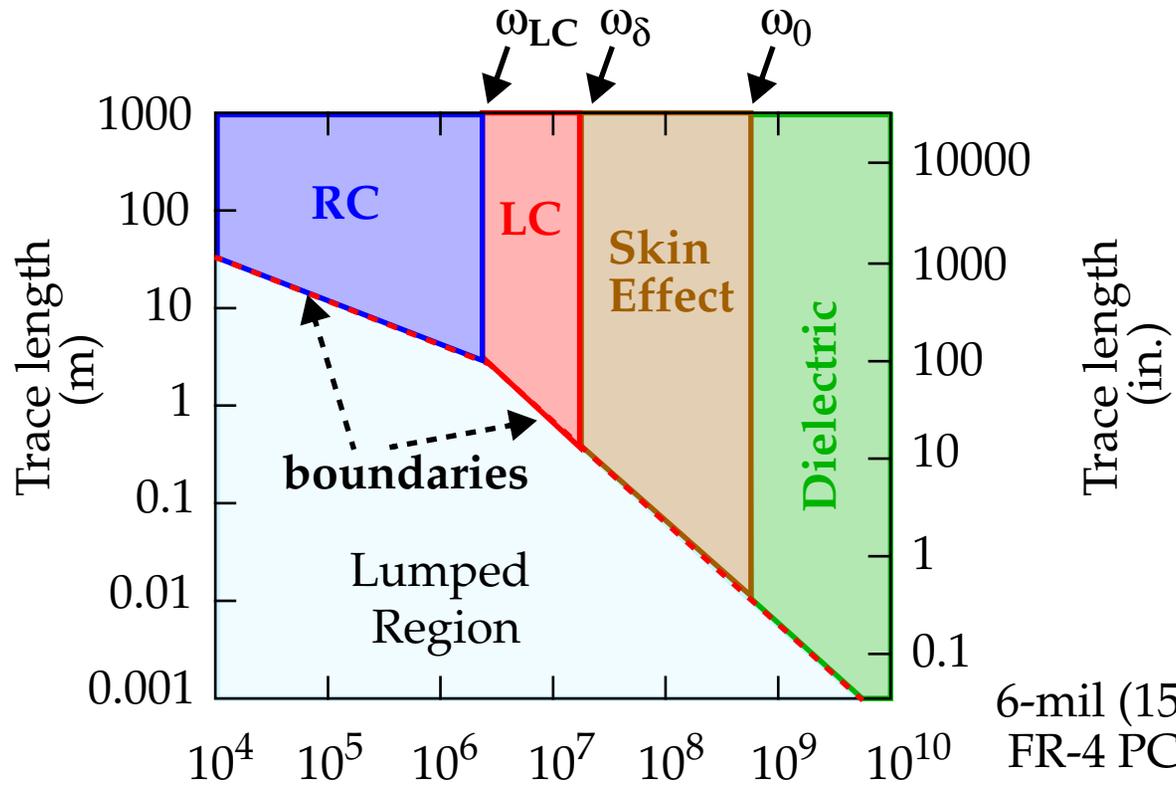
$$l_{LE} \approx \frac{\Delta}{\sqrt{\omega R_{DC} C}} \quad \text{for } (\omega < R_{DC}/L) \quad \text{(RC product dominates)}$$

$$l_{LE} \approx \frac{\Delta}{\omega \sqrt{LC}} \quad \text{for } (\omega > (R_{DC}/L)) \quad \text{(LC product dominates)}$$

These constraints ensure the transmission line delay **remains much smaller** than the signal's rise and fall times.



Lumped-Element Region



6-mil (150 μ m), 50- Ω , FR-4 PCB stripline

A discontinuity in the boundary is evident in the figure, creating a two-segment boundary.

The ω outside the sqrt() in the second constraint indicates that l decreases more rapidly beginning with LC mode.

Lumped-Element Region

Because the delay of the line is short, the source and load exert an almost *instantaneous* influence on the system behavior.

The *tight coupling* between the source and load impedances indicate that lumped-element operation rarely requires *termination*.

Except in cases involving very low-impedance drivers coupled to large reactive loads.

Bear in mind that *two* fully independent modes of propagation still exist (out and back).

The short line causes a portion of the signal's transition to propagate to the load, interact and reflect back to the source, affecting the input impedance.

In contrast, on long lines, the long transit time *disconnects* the source and load in the temporal sense.

Here, information about the load reflects back to the source too late to affect the progress of an individual rising or falling edge.

Lumped-Element Region: Input Impedance

Our objective is to examine the **input impedance** of a lumped-element structure under various conditions of loading.

The following portions of a Taylor-series expansion may be used to approximate H and H^{-1} in the lumped-element region

$$\frac{H^{-1} + H}{2} \approx 1 + \frac{(l\gamma)^2}{2}$$

$$\frac{H^{-1} - H}{2} \approx (l\gamma) + \frac{(l\gamma)^3}{6}$$

Applying these to our general equation for **input impedance**.

$$Z_{\text{in, loaded}} = Z_C \left(\frac{\left(\frac{H^{-1} + H}{2} \right) + \frac{Z_C}{Z_L} \left(\frac{H^{-1} - H}{2} \right)}{\left(\frac{H^{-1} - H}{2} \right) + \frac{Z_C}{Z_L} \left(\frac{H^{-1} + H}{2} \right)} \right)$$

Lumped-Element Region: Input Impedance

Neglecting all but the constant and linear terms yields

$$Z_{\text{in, loaded}} = Z_C \left\{ \frac{1 + \frac{Z_C}{Z_L}(l\gamma)}{(l\gamma) + \frac{Z_C}{Z_L}} \right\}$$

Under conditions that the line is **lightly loaded** ($Z_L \gg Z_C$), the right hand terms in the numerator and denominator vanish, leaving

$$Z_{\text{in, open-circuited}} \approx Z_C \left\{ \frac{1}{l\gamma} \right\}$$

Plugging in reveals that the input impedance of a short, unloaded line looks entire capacitive

$$Z_{\text{in, open-circuited}} \approx \sqrt{\frac{(j\omega L + R)}{j\omega C}} \left\{ \frac{1}{l\sqrt{(j\omega L + R)j\omega C}} \right\} = \frac{1}{l * j\omega C}$$

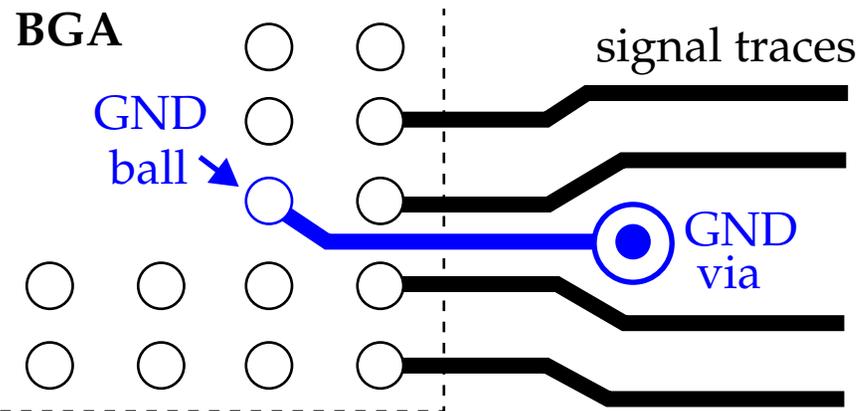


Lumped-Element Region: Input Impedance

And the total capacitance is the total distributed capacitance of the line, i.e., $l \cdot C$.

Remember, this works only when the line delay is short compared to the signal rise and fall time (1/6 and 1/3 at most) AND
The line is lightly loaded at its endpoint.

Consider the case when the line is short-circuited to ground at the far end.



Short 'jumper' connection is routed from the GND pin to a GND via.

This is commonly done (but not a good idea) because of congestion around the BGA pins

What is the effective input impedance of this trace leading to GND, from the perspective of the chip?

Lumped-Element Region: Input Impedance

Since the line is shorted, the impedance of the load is much lower than the line impedance, i.e., $Z_L \ll Z_C$.

This term inflates the right-hand terms, causing them to dominate

$$Z_{\text{in, loaded}} = Z_C \left\{ \frac{1 + \frac{Z_C}{Z_L}(l\gamma)}{(l\gamma) + \frac{Z_C}{Z_L}} \right\}$$

This yields a simple expression for input impedance.

$$Z_{\text{in, short-circuited}} \approx Z_C \{l\gamma\}$$

Plugging in shows the input impedance is either **inductive** or **resistive**, depending on the ratio of $j\omega L$ to R .

$$Z_{\text{in, short-circuited}} \approx l^*(j\omega L + R)$$

Lumped-Element Region: Input Impedance

In digital apps, the *inductance* of the trace is usually much more significant.

The amount of inductance is the total distributed inductance ($l \cdot L$) of the transmission line, defined by the trace and its return path.

This equation is useful for computing **ground-bounce** when a current $i(t)$ passes through the trace to GND.

In a third case, when the transmission line is properly terminated, ($Z_L = Z_C$), the numerator and denominator are equal yielding Z_C .

One final point is that for lines operated at frequencies below the onset of the LC region, the input impedance **is not constant**.

Rather it is a strong frequency-varying quantity with phase at 45 degrees.

Accurately matching the impedance Z_C in this region **is not trivial**, so its fortunate that most short lines do not need termination.

Lumped-Element Region: Circuit Gain

To compute the gain, substitute

$$\frac{H^{-1} + H}{2} \approx 1 + \frac{(l\gamma)^2}{2}$$

$$\frac{H^{-1} - H}{2} \approx (l\gamma) + \frac{(l\gamma)^3}{6}$$

into

$$G_{\text{FWD}} = \frac{v_3}{v_1} = \frac{1}{\left[\left(\frac{H^{-1} + H}{2} \right) \left(1 + \frac{Z_S}{Z_L} \right) + \left(\frac{H^{-1} - H}{2} \right) \left(\frac{Z_S}{Z_C} + \frac{Z_C}{Z_L} \right) \right]}$$

This yields

$$G = \left[\left(1 + \frac{Z_S}{Z_L} \right) + l\gamma \left(\frac{Z_S}{Z_C} + \frac{Z_C}{Z_L} \right) + \frac{(l\gamma)^2}{2} \left(1 + \frac{Z_S}{Z_L} \right) + \frac{(l\gamma)^3}{6} \left(\frac{Z_S}{Z_C} + \frac{Z_C}{Z_L} \right) \right]^{-1}$$

Lumped-Element Region: Circuit Gain

What are the conditions needed to achieve gain flatness?

As the term $l\gamma$ approaches zero, all terms associated with its various powers vanish, and the propagation function approaches

$$G = \frac{Z_L}{(Z_S + Z_L)}$$

This is exactly what you would expect if the source and load were directly connected (no line).

We assumed that the magnitude of the coefficient $l\gamma$ in the lumped element region remains less than $\Delta = 1/4$.

This allows you to ignore the right-most two elements in the gain Eq.

The second term can be ignored too if

$$\left| l\gamma \frac{Z_S}{Z_C} \right| \ll 1 \quad \text{and} \quad \left| l\gamma \frac{Z_C}{Z_L} \right| \ll 1 \quad \text{and} \quad |l\gamma| < 0.25$$

Lumped-Element Region: Circuit Gain

Inserting definitions for γ and Z_C

$$|Z_S| \ll \left| \frac{1}{l^* j\omega C} \right|$$

$$|l^*(j\omega L + R)| \ll |Z_L|$$

Therefore, for the line to not exert any deleterious influence over signal quality, these conditions must ALSO be met, above and beyond

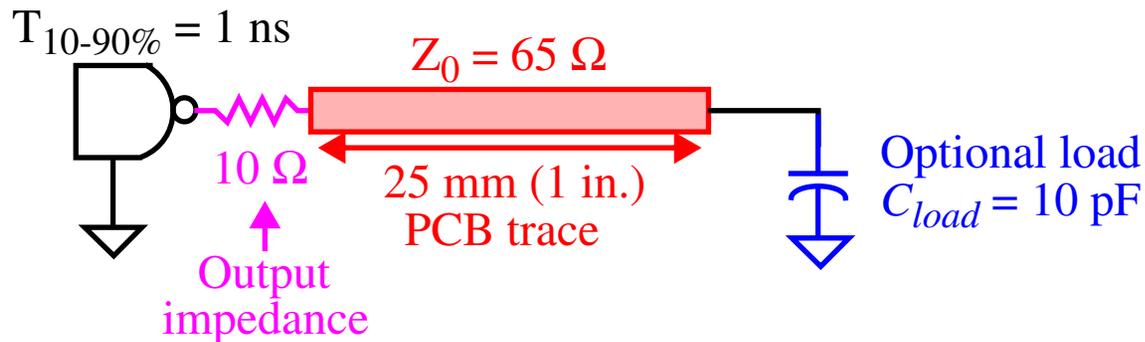
$$|l\gamma| < 0.25$$

In words:

- The **source impedance** of the driver MUST be *much smaller* than the impedance represented by the **total shunt capacitance** of the line.
- The **total series impedance** of the line MUST remain *much smaller* than the impedance of the **load**.

Lumped-Element Region

Example



Effective dielectric constant: 3.8

High frequency propagation velocity:

$$v_0 = \frac{c}{\sqrt{3.8}} = 1.54 \times 10^8 \text{ m/s}$$

DC resistance: $3 \Omega/\text{m}$

Operating frequency (corresponds to the center of the spectral lobe associated with each rising and falling edge)

$$\omega = \frac{2\pi * (0.35)}{1 \text{ ns}} = 2.2 \times 10^9 \text{ rad/s}$$

Lumped Element Region: Example

Compute transmission line parameters, L and C

$$L = \frac{Z_0}{v_0} = 422 \text{ nH/m} \qquad C = \frac{1}{Z_0 v_0} = 100 \text{ pF/m}$$

Since the *inductive effects* of the line far outweighs the *resistance*, you can approximate the magnitude of the propagation coefficient using

$$|l\gamma| = l\omega\sqrt{LC}$$

$$|l\gamma| = 0.025 * 2.2 \times 10^9 \sqrt{(422 \text{ nH/m})(100 \text{ pF/m})} = 0.357$$

This value is just outside the 'official' boundary of the lumped-element region at 0.25.

Check conditions

$$|Z_S| \ll \left| \frac{1}{l * j\omega C} \right|$$

$$|10 \Omega| \ll \left| \frac{1}{0.025 * 2.2 \times 10^9 * 100 \text{ pF/m}} \right| = 182 \Omega \qquad \text{Yes}$$

Lumped Element Region: Example

And

$$|l*(j\omega L + R)| \ll |Z_L|$$

For the case of no load capacitance (infinite Z_L), this condition clearly holds.

Therefore, for rise/fall times no faster than 1 ns, this microstrip without a load induces practically *no* distortion in the transmitted wfm.

What about the 10 pF case?

$$|Z_L| = \frac{1}{(2.2 \times 10^9)(10 \times 10^{-12})} = 45.5 \Omega \quad \longleftarrow Z_L = \frac{1}{j\omega C}$$

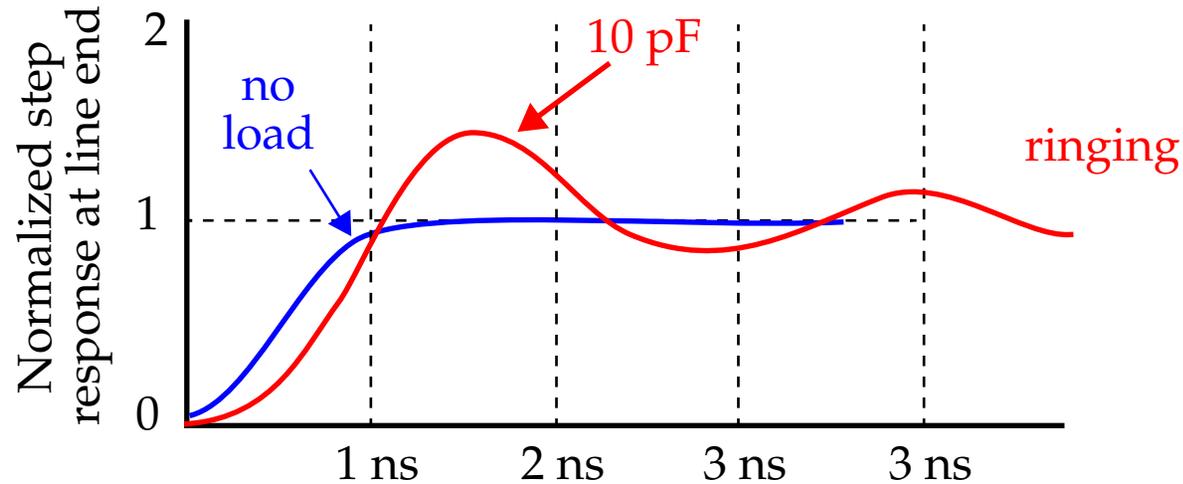
$$|l(j\omega L)| = 0.025 * 2.2 \times 10^9 * 422 \text{ nH/m} = 23.2 \Omega$$

Here, the magnitude of Z_L exceeds the series impedance of the line by only a small amount (2:1)

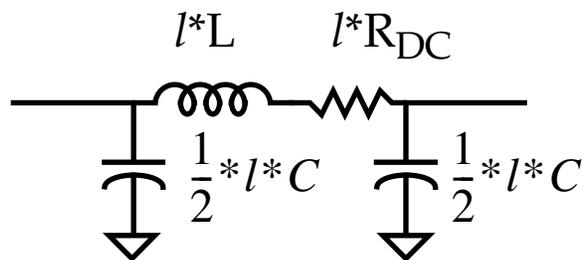
This implies the transmission line will have a noticeable effect.

Lumped Element Region: Example

Plotting



The *pi-model* can be used to approximate the behavior of a short transmission line



Lumped Element Region: Example

From our example, the values of the variables for the **unloaded** version are

$$l * L = 0.025 * 422 \text{ nH/m} = 10.6 \text{ nH}$$

$$\frac{1}{2}(l * C) = 0.5 * 0.025 * 100 \text{ pF/m} = 1.25 \text{ pF}$$

When driven by a low-impedance source, the capacitor on the left plays only a small role.

The main effect is the R-L-C series-resonant circuit formed by the output resistance of the driver, the series inductance and capacitor on the right.

The resonant frequency under **no loading**

$$\omega_{res} = \frac{1}{\sqrt{(l * L) \left(\frac{1}{2} l * C \right)}} = \frac{1}{\sqrt{10.6 \times 10^{-9} * 1.25 \times 10^{-12}}} = 8.7 \times 10^9 \text{ rad/s}$$

This is well above the *spectral center of gravity* of the rising and falling edges ($2.2 \times 10^9 \text{ rad/s}$), so resonance does not occur.

Lumped Element Region: Example

With a 10 pF load, the situation changes.

The new load capacitance *adds* to the capacitance on the right in the *pi* model, reducing the resonance frequency

$$\omega_{res} = \frac{1}{\sqrt{(l*L)\left(\frac{1}{2}l*C + C_{load}\right)}} = \frac{1}{\sqrt{10.6 \times 10^{-9} * 11.25 \times 10^{-12}}} = 2.9 \times 10^9 \text{ rad/s}$$

This is close to the bandwidth of the driver at 2.2×10^9 rad/s.

The resonance is obvious in the plot.

The period of the resonance is

$$\frac{2\pi}{\omega_{res}} = \frac{2\pi}{2.9 \times 10^9 \text{ rad/s}} = 2.2 \text{ ns}$$

This corroborates the ringing observable in the plot.